

ON SOME CIRCULAR SUMMATION FORMULAS FOR THETA FUNCTIONS

YUDHISTHIRA JAMUDULIA AND S. N. FATHIMA

ABSTRACT. In his lost notebook, Ramanujan claimed that the “circular” summation of n^{th} power of his symmetric theta function $f(a, b)$ satisfies a factorization of the form $f(a, b)F(ab)$. In this paper, we obtain new circular summation formula of theta functions using the theory of elliptic functions. As an application, we also obtain few interesting identity of the theta functions.

2000 MATHEMATICS SUBJECT CLASSIFICATION. Primary:
 11F27; Secondary: 11F20, 33E05.

KEYWORDS AND PHRASES. Circular summation,
 Elliptic functions, Theta functions.

1. INTRODUCTION

In Ramanujan’s notation [2, Ch.16, pp.34], we define the general theta function by

$$(1) \quad f(a, b) := \sum_{n=-\infty}^{\infty} a^{n(n+1)/2} b^{n(n-1)/2}, \quad |ab| < 1.$$

For $q = e^{\pi i \tau}$ and $\operatorname{Im}(\tau) > 0$, the classical Jacobi’s theta functions $\theta_i(z|\tau)$, $i = 1, 2, 3, 4$ are defined as follows:

$$(2) \quad \theta_1(z|\tau) = -iq^{1/4} \sum_{m=-\infty}^{\infty} (-1)^m q^{m(m+1)} e^{(2m+1)iz},$$

$$(3) \quad \theta_2(z|\tau) = q^{1/4} \sum_{m=-\infty}^{\infty} (-1)^m q^{m(m+1)} e^{(2m+1)iz},$$

$$(4) \quad \theta_3(z|\tau) = \sum_{m=-\infty}^{\infty} q^{m^2} e^{2miz},$$

$$(5) \quad \theta_4(z|\tau) = \sum_{m=-\infty}^{\infty} (-1)^m q^{m^2} e^{2miz}.$$

We get the following properties of $\theta_i(z|\tau), i = 1, 2, 3, 4$ employing (2)-(5):

- $$(6) \quad \theta_1(z + \pi|\tau) = -\theta_1(z|\tau), \quad \theta_1(z + \pi\tau|\tau) = -q^{-1}e^{-2iz}\theta_1(z|\tau),$$
- $$(7) \quad \theta_2(z + \pi|\tau) = -\theta_2(z|\tau), \quad \theta_2(z + \pi\tau|\tau) = q^{-1}e^{-2iz}\theta_2(z|\tau),$$
- $$(8) \quad \theta_3(z + \pi|\tau) = \theta_3(z|\tau), \quad \theta_3(z + \pi\tau|\tau) = q^{-1}e^{-2iz}\theta_3(z|\tau),$$
- $$(9) \quad \theta_4(z + \pi|\tau) = \theta_4(z|\tau), \quad \theta_4(z + \pi\tau|\tau) = -q^{-1}e^{-2iz}\theta_4(z|\tau).$$

Applying induction on (6)-(9), we obtain

- $$(10) \quad \theta_1(z + n\pi\tau|\tau) = (-1)^n q^{-n^2} e^{-2niz}\theta_1(z|\tau),$$
- $$(11) \quad \theta_2(z + n\pi\tau|\tau) = q^{-n^2} e^{-2niz}\theta_2(z|\tau),$$
- $$(12) \quad \theta_3(z + n\pi\tau|\tau) = q^{-n^2} e^{-2niz}\theta_3(z|\tau),$$
- $$(13) \quad \theta_4(z + n\pi\tau|\tau) = (-1)^n q^{-n^2} e^{-2niz}\theta_4(z|\tau).$$

On page 54 of his lost notebook [14] (see also [1, pp.337]), Ramanujan recorded a statement which is now known as Ramanujan's circular summation:

Theorem 1.1. For any positive integer $n \geq 2$, if

$$U_r = a^{r(r+1)/2n} b^{r(r-1)/2n} \text{ and } V_r = a^{r(r-1)/2n} b^{r(r+1)/2n},$$

then

$$\sum_{r=0}^{n-1} U_r^n f^n \left(\frac{U_{n+r}}{U_r}, \frac{V_{n-r}}{U_r} \right) = f(a, b) F_n(ab),$$

where

$$F_n(q) = 1 + 2nq^{(n-1)/2} + \dots, n > 3.$$

Ramanujan's circular summation can be restated in terms of classical theta function $\theta_3(z|\tau)$ defined by (4).

Theorem 1.2. For any positive integer $n \geq 2$,

$$\sum_{k=0}^{n-1} q^{k^2} e^{2kiz} \theta_3^n(z + k\pi\tau|n\tau) = F_n(\tau) \theta_3(z|\tau),$$

where

$$F_n(\tau) = 1 + 2nq^{n-1} + \dots.$$

The proof of Theorem 1.1 was given by S. S. Rangachari in [15], by using Mumford's theory of theta functions [12] and few results on weight polynomials in coding theory. Later, Son [18] gave much elementary proof of Theorem 1.1. Recently, Xu [19] has given a very elementary and neat proof of the circular summation formula.

Applying the theory of elliptic functions, H. H. Chan, Z. G. Liu and S. T. Ng proved a dual form of Ramanujan's circular summation in. M. Boon, M. L. Glasser, J. Zak and I. J. Zucker [8] have proved an additive decomposition of θ_3 . A general result that unifies the results of [8] and [9] is proved by Zeng [20]: For a, b, n and k any positive integers with $k = a + b$,

$$\sum_{s=0}^{kn-1} \theta_3^a \left(\frac{z}{kn} + \frac{y}{a} + \frac{\pi s}{kn} \middle| \frac{\tau}{kn^2} \right) \theta_3^b \left(\frac{z}{kn} - \frac{y}{b} + \frac{\pi s}{kn} \middle| \frac{\tau}{kn^2} \right) = \mathcal{C}_{33} \left(a, b; \frac{y}{ab}, \frac{\tau}{kn^2} \right) \theta_3(z|\tau),$$

where

$$\mathcal{C}_{33}(a, b; y, \tau) = kn \sum_{\substack{m_1, \dots, m_a, n_1, \dots, n_b = -\infty \\ m_1 + \dots + m_a + n_1 + \dots + n_b = 0}}^{+\infty} q^{m_1^2 + \dots + m_a^2 + n_1^2 + \dots + n_b^2} e^{2k(m_1 + \dots + m_a)iy}.$$

For more recent works on Ramanujan's circular summation one may refer [6], [7], [10], [13], [11], [16], [22], [23], [4], [9], [5] and [21].

Motivated by these works, in particular the works of Y. Cai, Y. Q. Bi and Q-M Luo [5], we obtain new Ramanujan's summation summation for four theta functions employing elliptic functions. In Section 2, we obtain our main results. In Section 3, we obtain interesting identities from the main results. Finally, we conclude the paper with some application.

2. MAIN RESULTS

Theorem 2.1. Let a, b, c, l, m and n are positive integers with $a+b+c=m$. If a, b, c are even, then we have

$$(14) \quad \begin{aligned} & \sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \theta_2^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \\ & \times \theta_3^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) = \mathcal{F}_{123} \left(a, b, c; \frac{y}{abc}, \frac{\tau}{lmn^2} \right) \theta_3(z|\tau), \end{aligned}$$

where

$$(15) \quad \begin{aligned} & \mathcal{F}_{123}(a, b, c; y, \tau) \\ & = lmni^a q^{\frac{a+b}{4}} \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a} \\ & \quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a + v_1 + \dots + v_b} \\ & \quad \times e^{2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c) + abc\}iy}. \end{aligned}$$

Theorem 2.2. Let a, b, c, l, m and n are positive integers with $a+b+c=m$. If a, b, c are even, then we have

$$(16) \quad \begin{aligned} & \sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \theta_2^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \\ & \times \theta_4^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) = \mathcal{F}_{124} \left(a, b, c; \frac{y}{abc}, \frac{\tau}{lmn^2} \right) \theta_3(z|\tau), \end{aligned}$$

where

$$\begin{aligned}
 \mathcal{F}_{124}(a, b, c; y, \tau) = & lmni^a q^{\frac{a+b}{4}} \\
 & \times \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a + w_1 + \dots + w_c} \\
 & \quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a + v_1 + \dots + v_b} \\
 (17) \quad & \quad \times e^{2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c) + abc\}iy}.
 \end{aligned}$$

Theorem 2.3. Let a, b, c, l, m and n are positive integers with $a+b+c = m$. If a, b, c are even, then we have

$$\begin{aligned}
 (18) \quad & \sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \theta_3^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \\
 & \times \theta_4^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) = \mathcal{F}_{134} \left(a, b, c; \frac{y}{abc}, \frac{\tau}{lmn^2} \right) \theta_3(z|\tau),
 \end{aligned}$$

where

$$\begin{aligned}
 \mathcal{F}_{134}(a, b, c; y, \tau) = & lmni^a q^{\frac{a}{4}} \\
 & \times \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a + w_1 + \dots + w_c} \\
 & \quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a} \\
 (19) \quad & \quad \times e^{[2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c)\} + abc]iy}.
 \end{aligned}$$

Theorem 2.4. Let a, b, c, l, m and n are positive integers with $a+b+c = m$. If a, b, c are even, then we have

$$\begin{aligned}
 (20) \quad & \sum_{s=0}^{lmn-1} \theta_2^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \theta_3^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) \\
 & \times \theta_4^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \mid \frac{\tau}{lmn^2} \right) = \mathcal{F}_{234} \left(a, b, c; \frac{y}{abc}, \frac{\tau}{lmn^2} \right) \theta_3(z|\tau),
 \end{aligned}$$

where

$$\begin{aligned}
 \mathcal{F}_{234}(a, b, c; y, \tau) &= lmni^{\frac{a}{4}} \\
 &= \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a = 0}}^{+\infty} (-1)^{w_1 + \dots + w_c} \\
 & \quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a} \\
 (21) \quad & \quad \times e^{[2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c)\} + abc]iy}.
 \end{aligned}$$

Theorem 2.5. Let a, b, c, d, k, l, m and n are positive integers with $a + b + c + d = m$. If a, b, c, d are even, then we have

$$\begin{aligned} & \sum_{s=0}^{klmn-1} \theta_1^a\left(\frac{z}{klmn} + \frac{y}{a} + \frac{\pi s}{klmn^2} \mid \frac{\tau}{klmn^2}\right) \theta_2^b\left(\frac{z}{klmn} + \frac{y}{b} + \frac{\pi s}{klmn^2} \mid \frac{\tau}{klmn^2}\right) \\ & \quad \theta_3^c\left(\frac{z}{klmn} + \frac{y}{c} + \frac{\pi s}{klmn^2} \mid \frac{\tau}{klmn^2}\right) \theta_4^d\left(\frac{z}{klmn} + \frac{y}{d} + \frac{\pi s}{klmn^2} \mid \frac{\tau}{klmn^2}\right) \\ (22) \quad & \quad = \mathcal{F}_{1234}\left(a, b, c, d; \frac{y}{abcd}, \frac{\tau}{klmn^2}\right) \theta_3(z|\tau), \end{aligned}$$

where

$$\begin{aligned} \mathcal{F}_{1234}(a, b, c, d; y, \tau) &= klmni^a q^{\frac{a+b}{4}} \\ &\times \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c, x_1, \dots, x_d = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c + x_1 + \dots + x_d) \\ + a + b = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a + x_1 + \dots + x_d} \\ &\quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + x_1^2 + \dots + x_d^2 + u_1 + \dots + u_a + v_1 + \dots + v_b} \\ (23) \quad &\quad \times e^{[2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c)\} + abc]iy}. \end{aligned}$$

Proof: Let $f(z)$ be the left side of (14). Then

$$\begin{aligned} f(z + \pi) &= \\ &\sum_{s=1}^{lmn-1} \theta_1^a\left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) \theta_2^b\left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) \\ &\quad \theta_3^c\left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) + \theta_1^a\left(\frac{z}{lmn} + \frac{y}{a} \mid \frac{\tau}{lmn^2}\right) \\ (24) \quad &\quad \theta_2^b\left(\frac{z}{lmn} + \frac{y}{b} \mid \frac{\tau}{lmn^2}\right) \theta_3^c\left(\frac{z}{lmn} + \frac{y}{c} \mid \frac{\tau}{lmn^2}\right). \end{aligned}$$

$$\begin{aligned} f(z + \pi) &= \\ &\sum_{s=1}^{lmn-1} \theta_1^a\left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) \theta_2^b\left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) \\ &\quad \theta_3^c\left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn^2} \mid \frac{\tau}{lmn^2}\right) + (-1)^{a+b} \theta_1^a\left(\frac{z}{lmn} + \frac{y}{a} \mid \frac{\tau}{lmn^2}\right) \\ (25) \quad &\quad \theta_2^b\left(\frac{z}{lmn} + \frac{y}{b} \mid \frac{\tau}{lmn^2}\right) \theta_3^c\left(\frac{z}{lmn} + \frac{y}{c} \mid \frac{\tau}{lmn^2}\right). \end{aligned}$$

Since a and b are even, we have from (24) and (25)

$$(26) \quad f(z + \pi) = f(z).$$

Again from (24) and a, b, c even, we have

$$\begin{aligned}
 f(z + \pi\tau) &= \sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} + n\pi \frac{\tau}{lmn^2} \middle| \frac{\tau}{lmn^2} \right) \times \\
 &\quad \theta_2^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} + n\pi \frac{\tau}{lmn^2} \middle| \frac{\tau}{lmn^2} \right) \theta_3^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} + n\pi \frac{\tau}{lmn^2} \middle| \frac{\tau}{lmn^2} \right) \\
 &= q^{-1} e^{-2iz} \sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) \theta_2^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) \\
 &\quad \times \theta_3^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) = q^{-1} e^{-2iz} f(z).
 \end{aligned} \tag{27}$$

By (26) and (27), we have constructed an elliptic function $f(z)/\theta_3(z|\tau)$ with double periods π and $\pi\tau$ and only have a simple pole at $z = \pi/2 + \pi\tau/2$ in the period parallelogram. Hence the function $f(z)/\theta_3(z|\tau)$ is a constant, say $F_{123}(a, b, c; y, \tau)$, i.e.

$$\frac{f(z)}{\theta_3(z|\tau)} = F_{123}(a, b, c; y, \tau) \theta_3(z|\tau),$$

or, equivalently

$$f(z) = F_{123}(a, b, c; y, \tau) \theta_3(z|\tau).$$

Hence

$$\begin{aligned}
 &\sum_{s=0}^{lmn-1} \theta_1^a \left(\frac{z}{lmn} + \frac{y}{a} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) \theta_2^b \left(\frac{z}{lmn} + \frac{y}{b} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) \\
 &\quad \theta_3^c \left(\frac{z}{lmn} + \frac{y}{c} + \frac{\pi s}{lmn} \middle| \frac{\tau}{lmn^2} \right) = F_{123}(a, b, c; y, \tau) \theta_3(z|\tau).
 \end{aligned} \tag{28}$$

Employing (2), (3) and (5), we obtain

$$\begin{aligned}
 F_{123}(a, b, c; y, \tau) &\sum_{m=-\infty}^{\infty} q^{m^2} e^{2miz} \\
 &= (-1)^a i^a q^{\frac{a+b}{4lmn^2}} \sum_{s=0}^{lmn-1} \sum_{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty}^{\infty} (-1)^{u_1 + \dots + u_c} \\
 &\quad \times q^{\frac{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_a^2 + u_1 + \dots + u_a + v_1 + \dots + v_b}{lmn^2}} \\
 &\quad \times e^{\frac{\{2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b\}}{lmn} iz} \\
 &\quad \times e^{\left\{ \frac{2(u_1 + \dots + u_a) + a}{a} + \frac{2(v_1 + \dots + v_b) + b}{b} + \frac{w_1 + \dots + w_a}{c} \right\} iy} \\
 &\quad \times e^{\frac{\{2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b\}}{lmn} i\pi s}.
 \end{aligned} \tag{29}$$

The constant term on both sides of (29), we have

$$\begin{aligned}
& F_{123}(a, b, c; y, \tau) \\
&= lmni^a q^{\frac{a+b}{4lmn^2}} \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a} \\
&\quad \times q^{\frac{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a + v_1 + \dots + v_b}{lmn^2}} \\
&\quad \times e^{\frac{2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c) + abc\}}{abc} iy}.
\end{aligned}$$

It is clear that

$$F_{123}(a, b, c; y, \tau) = \mathcal{F}_{123}\left(a, b, c; \frac{y}{abc}, \frac{\tau}{lmn^2}\right),$$

where

$$\begin{aligned}
& \mathcal{F}_{123}(a, b, c; y, \tau) \\
&= lmni^a q^{\frac{a+b}{4}} \sum_{\substack{u_1, \dots, u_a, v_1, \dots, v_b, w_1, \dots, w_c = -\infty \\ 2(u_1 + \dots + u_a + v_1 + \dots + v_b + w_1 + \dots + w_c) + a + b = 0}}^{+\infty} (-1)^{u_1 + \dots + u_a} \\
&\quad \times q^{u_1^2 + \dots + u_a^2 + v_1^2 + \dots + v_b^2 + w_1^2 + \dots + w_c^2 + u_1 + \dots + u_a + v_1 + \dots + v_b} \\
&\quad \times e^{2\{bc(u_1 + \dots + u_a) + ac(v_1 + \dots + v_b) + ab(w_1 + \dots + w_c) + abc\} iy}.
\end{aligned}$$

This complete the proof of Theorem 2.1.

Proof of Theorem 2.2 – 2.5 are similar.

3. INTERESTING IDENTITIES OF MAIN RESULTS

L. C. Shen [17] has obtained the Fourier series expansion of triple product of Jacobi theta functions. These expansion can be converted into difference of theta functions as follows:

Lemma 3.1. From (2), (3), (4) and (5), we have

$$\begin{aligned}
(30) \quad & \theta_1(z|\tau)\theta_2(z|\tau)\theta_3(z|\tau) \\
&= -iq^{3/2}(q^2; q^2)_\infty^2 \{e^{4iz}\theta_4(3z + 2\pi\tau|3\tau) - e^{-4iz}\theta_4(3z - 2\pi\tau|3\tau)\},
\end{aligned}$$

$$\begin{aligned}
(31) \quad & \theta_1(z|\tau)\theta_2(z|\tau)\theta_4(z|\tau) \\
&= iq^{3/2}(q^2; q^2)_\infty^2 \{e^{4iz}\theta_3(3z + 2\pi\tau|3\tau) - e^{-4iz}\theta_3(3z - 2\pi\tau|3\tau)\},
\end{aligned}$$

$$\begin{aligned}
(32) \quad & \theta_1(z|\tau)\theta_3(z|\tau)\theta_4(z|\tau) \\
&= iq^{5/4}(q^2; q^2)_\infty^2 \{e^{2iz}\theta_2(3z + \pi\tau|3\tau) - e^{-2iz}\theta_2(3z - \pi\tau|3\tau)\},
\end{aligned}$$

$$\begin{aligned}
(33) \quad & \theta_2(z|\tau)\theta_3(z|\tau)\theta_4(z|\tau) \\
&= -iq^{1/2}(q^2; q^2)_\infty^2 \{e^{2iz}\theta_1(3z + \pi\tau|3\tau) - e^{-2iz}\theta_1(3z - \pi\tau|3\tau)\}.
\end{aligned}$$

Proof: We have from [17, Proposition 2.1]

$$\begin{aligned}
& \theta_1(z|\tau)\theta_2(z|\tau)\theta_3(z|\tau) \\
&= 2q^{3/2}(q^2;q^2)_\infty^2 \sum_{n=-\infty}^{\infty} (-1)^n q^{3n^2+4n} \sin(6n+4)z \\
&= -iq^{3/2}(q^2;q^2)_\infty^2 \sum_{n=-\infty}^{\infty} (-1)^n q^{3n^2+4n} (e^{(6n+4)iz} - e^{-(6n+4)iz}) \\
&= -iq^{3/2}(q^2;q^2)_\infty^2 \left(e^{4iz} \sum_{n=-\infty}^{\infty} (-1)^n q^{3n^2} e^{2ni(2\pi\tau+3z)} \right. \\
&\quad \left. - e^{-4iz} \sum_{n=-\infty}^{\infty} (-1)^n q^{3n^2} e^{2ni(2\pi\tau-3z)} \right). \tag{34}
\end{aligned}$$

We obtain (30) by replacing n by $-n$ in second summation and by the definition of $\theta_4(z|\tau)$ (5). Similarly, (31) and (33) can be proved. Now

$$\begin{aligned}
& \theta_1(z|\tau)\theta_3(z|\tau)\theta_4(z|\tau) \\
&= 2q^{1/4}(q^2;q^2)_\infty^2 \sum_{n=-\infty}^{\infty} q^{3n^2+4n} \sin(6n+1)z \\
&= iq^{1/4}(q^2;q^2)_\infty^2 \left(\sum_{n=-\infty}^{\infty} q^{3n^2+n} e^{-(6n+1)iz} - \sum_{n=-\infty}^{\infty} q^{3n^2+n} e^{(6n+1)iz} \right) \\
&= iq^{5/4}(q^2;q^2)_\infty^2 \left(e^{2iz} \sum_{n=-\infty}^{\infty} q^{3n^2-3n} e^{i(2n-1)(3z+\pi\tau)} \right. \\
&\quad \left. - e^{-2iz} \sum_{n=-\infty}^{\infty} q^{3n^2-3n} e^{i(2n-1)(3z-\pi\tau)} \right). \tag{35}
\end{aligned}$$

(32) is achieved by replacing n by $-n$ in the first summation and n by $n-1$ in the second summation and employing (3).

Theorems 2.1 – 2.4 are closely related with the Lemma 3.1.

Theorem 3.2. Setting $a = b = c = t$ in (14) and employing (30), we obtain

$$\begin{aligned}
& \sum_{s=0}^{lmn-1} \left(e^{4i(\frac{z}{lmn} + \frac{y}{t} + \frac{\pi s}{lmn})} \theta_4 \left(3 \left(\frac{z}{lmn} + \frac{y}{t} + \frac{\pi s}{lmn} \right) + \frac{2\pi\tau}{lmn^2} \mid \frac{3\tau}{lmn^2} \right) \right. \\
&\quad \left. - e^{-4i(\frac{z}{lmn} + \frac{y}{t} + \frac{\pi s}{lmn})} \theta_4 \left(3 \left(\frac{z}{lmn} + \frac{y}{t} + \frac{\pi s}{lmn} \right) - \frac{2\pi\tau}{lmn^2} \mid \frac{3\tau}{lmn^2} \right) \right)^t \\
&= \mathcal{K}_{123} \left(t, t, t; \frac{y}{t^3}, \frac{\tau}{lmn^2} \right) \theta_3(z|\tau), \tag{36}
\end{aligned}$$

where

$$\begin{aligned}
 & \mathcal{K}_{123}(t, t, t; y, \tau) \\
 &= \frac{l m n}{q^t (q^2; q^2)_\infty^{2t}} \sum_{\substack{u_1, \dots, u_t, v_1, \dots, v_t, w_1, \dots, w_t = -\infty \\ u_1 + \dots + u_t + v_1 + \dots + v_t + w_1 + \dots + w_t + t = 0}}^{+\infty} (-1)^{u_1 + \dots + u_t + w_1 + \dots + w_t} \\
 &\quad \times q^{u_1^2 + \dots + u_t^2 + v_1^2 + \dots + v_t^2 + w_1^2 + \dots + w_t^2 + u_1 + \dots + u_t + v_1 + \dots + v_t} \\
 (37) \quad &\quad \times e^{2\{t^2(u_1 + \dots + u_t + v_1 + \dots + v_t + w_1 + \dots + w_t) + t\}iy}.
 \end{aligned}$$

On setting $a = b = c = t$ in identities in (16), (18) and (20) and employing identities (31), (32) and (33) respectively, we obtain similar results.

4. APPLICATIONS OF MAIN RESULTS

In this Section, we give some special cases of Theorems 2.1 – 2.5 and obtain some interesting identities of theta functions.

Corollary 4.1. For l and n positive even integers, we have

$$\begin{aligned}
 & \sum_{s=0}^{6ln-1} \theta_1^2\left(\frac{z}{6ln} + \frac{y}{2} + \frac{\pi s}{6ln} \mid \frac{\tau}{6ln^2}\right) \theta_2^2\left(\frac{z}{6ln} + \frac{y}{2} + \frac{\pi s}{6ln} \mid \frac{\tau}{6ln^2}\right) \\
 (38) \quad & \theta_3^2\left(\frac{z}{6ln} + \frac{y}{2} + \frac{\pi s}{6ln} \mid \frac{\tau}{6ln^2}\right) = 6ln\theta_1^2(0 \mid \frac{\tau}{6ln^2}) \theta_2^2(0 \mid \frac{\tau}{6ln^2}) \theta_3^2(0 \mid \frac{\tau}{6ln^2}) \theta_3(z \mid \tau)
 \end{aligned}$$

Proof: Setting $a = b = c = 2$ in (14)

$$\begin{aligned}
 & \mathcal{F}_{123}(2, 2, 2; y, \tau) = -6lnq \\
 & \quad \sum_{\substack{u_1, u_2, v_1, v_2, w_1, w_2 = -\infty \\ u_1 + u_2 + v_1 + v_2 + w_1 + w_2 + 2 = 0}}^{+\infty} (-1)^{u_1 + u_2} q^{u_1^2 + u_2^2 + v_1^2 + v_2^2 + w_1^2 + w_2^2 + u_1 + u_2 + v_1 + v_2} \\
 & \quad \times e^{8\{(u_1 + u_2) + (v_1 + v_2) + (w_1 + w_2) + 2\}iy} \\
 &= -6lnq \sum_{u_1, u_2, v_1, v_2, w_1, w_2 = -\infty}^{+\infty} (-1)^{u_1 + u_2} q^{u_1^2 + u_2^2 + v_1^2 + v_2^2 + w_1^2 + w_2^2 + u_1 + u_2 + v_1 + v_2} \\
 (39) \quad &= 6ln\theta_1^2(0 \mid \tau) \theta_2^2(0 \mid \tau) \theta_3^2(0 \mid \tau).
 \end{aligned}$$

Changing τ by $\frac{\tau}{6ln^2}$ in (39), we obtain Corollary 4.1.

Setting $l = n = 1$ in Corollary 4.1,

$$\begin{aligned}
 & \sum_{s=0}^5 \theta_1^2\left(\frac{z}{6} + \frac{y}{2} + \frac{\pi s}{6} \mid \frac{\tau}{6}\right) \theta_2^2\left(\frac{z}{6} + \frac{y}{2} + \frac{\pi s}{6} \mid \frac{\tau}{6}\right) \theta_3^2\left(\frac{z}{6} + \frac{y}{2} + \frac{\pi s}{6} \mid \frac{\tau}{6}\right) \\
 (40) \quad &= 6\theta_1^2(0 \mid \frac{\tau}{6}) \theta_2^2(0 \mid \frac{\tau}{6}) \theta_3^2(0 \mid \frac{\tau}{6}) \theta_3(z \mid \tau).
 \end{aligned}$$

Setting $z \mapsto 6z$, $y \mapsto 2y$ and $\tau \mapsto 6\tau$ in (40) and simplifying, we obtain

$$\begin{aligned}
& \theta_1^2(z+y|\tau)\theta_2^2(z+y|\tau)\theta_3^2(z+y|\tau) + \theta_1^2(z+y|\tau)\theta_2^2(z+y|\tau)\theta_4^2(z+y|\tau) \\
& + \theta_1^2\left(z+y-\frac{\pi}{3}|\tau\right)\theta_2^2\left(z+y-\frac{\pi}{3}|\tau\right)\theta_4^2\left(z+y-\frac{\pi}{3}|\tau\right) + \theta_1^2\left(z+y+\frac{\pi}{3}|\tau\right) \\
& \theta_2^2\left(z+y+\frac{\pi}{3}|\tau\right)\theta_3^2\left(z+y+\frac{\pi}{3}|\tau\right) + \theta_1^2\left(z+y-\frac{\pi}{3}|\tau\right)\theta_2^2\left(z+y-\frac{\pi}{3}|\tau\right) \\
& \theta_3^2\left(z+y-\frac{\pi}{3}|\tau\right) + \theta_1^2\left(z+y-\frac{\pi}{6}|\tau\right)\theta_2^2\left(z+y-\frac{\pi}{6}|\tau\right)\theta_3^2\left(z+y-\frac{\pi}{6}|\tau\right) \\
(41) \quad & = 6\theta_1^2(0|\tau)\theta_2^2(0|\tau)\theta_3^2(0|\tau)\theta_3(6z|6\tau).
\end{aligned}$$

Setting $y = 0$ in (41), we obtain

$$\begin{aligned}
& \theta_1^2\left(z+\frac{\pi}{6}|\tau\right)\theta_2^2\left(z+\frac{\pi}{6}|\tau\right)\theta_3^2\left(z+\frac{\pi}{6}|\tau\right) + \theta_1^2\left(z-\frac{\pi}{6}|\tau\right)\theta_2^2\left(z-\frac{\pi}{6}|\tau\right) \\
& \theta_3^2\left(z-\frac{\pi}{6}|\tau\right) = \theta_1^2\left(z-\frac{\pi}{3}|\tau\right)\theta_2^2\left(z-\frac{\pi}{3}|\tau\right)\theta_4^2\left(z-\frac{\pi}{3}|\tau\right) + \theta_1^2\left(z-\frac{\pi}{3}|\tau\right) \\
& \theta_2^2\left(z-\frac{\pi}{3}|\tau\right)\theta_4^2\left(z-\frac{\pi}{3}|\tau\right).
\end{aligned}$$

More similar identities can be obtain from Theorem 2.2 – 2.5.

Remark: The Jacobi transformation formulas for theta functions on applying Jacobi imaginary transformation formulas are given by

$$\begin{aligned}
\theta_1\left(\frac{z}{\tau} - \frac{1}{\tau}\right) &= -i\sqrt{-i\tau}e^{iz^2/\pi\tau}\theta_1(z|\tau), \\
\theta_2\left(\frac{z}{\tau} - \frac{1}{\tau}\right) &= \sqrt{-i\tau}e^{iz^2/\pi\tau}\theta_4(z|\tau), \\
\theta_3\left(\frac{z}{\tau} - \frac{1}{\tau}\right) &= \sqrt{-i\tau}e^{iz^2/\pi\tau}\theta_3(z|\tau), \\
\theta_4\left(\frac{z}{\tau} - \frac{1}{\tau}\right) &= \sqrt{-i\tau}e^{iz^2/\pi\tau}\theta_2(z|\tau).
\end{aligned}$$

Using the above identities, we can obtain imaginary transformation formulas of our Main results.

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DEPARTMENT OF MATHEMATICS, RAMANUJAN SCHOOL OF
MATHEMATICAL SCIENCES, PONDICHERRY UNIVERSITY, PUDUCHERRY
- 605 014, INDIA

E-mail address: `yudhis4581@yahoo.co.in`

DEPARTMENT OF MATHEMATICS, RAMANUJAN SCHOOL OF
MATHEMATICAL SCIENCES, PONDICHERRY UNIVERSITY, PUDUCHERRY
- 605 014, INDIA

E-mail address: `fathima.mat@pondiuni.edu.in`